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Introduction

Assembly lines are production systems developed to meet the requirements of mankind, which continue to grow day by day. The demand for greater product variability and shorter life cycles has caused traditional production methods to be replaced with assembly lines. The aims of these systems are to manufacture products at production rates in the shortest time, in the most productive way, cheaply and with the quality required. Since assembly line balancing is an NP-hard problem, some heuristic methods are still needed to solve large scale assembly line balancing problems.

An assembly line consists of a number of workstations which are arranged along a conveyor belt, or similar material transportation equipment, in order to obtain a sequence of finished product types. The work pieces are moved from station to station and at each one certain operations are performed in view of some constraints. The first primary constraint is the cycle time. The cycle time is the time interval between finishing two units or the maximum available time

Assembly Line Balancing in a Clothing Company

Abstract

In this study, two heuristic assembly line balancing techniques known as the "Ranked Positional Weight Technique", developed by Helgeson and Birnie, and the "Probabilistic Line Balancing Technique", developed by El-Sayed and Boucher, were applied to solve the problem of multi-model assembly line balancing in a clothing company for two models. Information about definitions and solution methods related to assembly line balancing problems is given. The aim of this article is the comparison of the efficiencies of two different procedures applied for the first time to solve line balancing in a clothing company. By using both methods, different restrictions are taken into consideration and two different line balancing results are reached. The balancing results are compared with each other.

Key words: assembly line, balancing techniques, multi-model assembly line, clothing company, balancing procedure efficiency.

for the production of any work piece at any workstation. When assigning work tasks to the stations, care must be taken that the total station time, which equals the sum of the processing times of each task performed at the station, should not exceed the cycle time [1]. Besides cycle time, precedence relations are the other primary constraints. Some tasks can only be started after other tasks have been finished [2].

An assembly line can be defined as a system which is formed by arranging workstations along a line. At these workstations, work pieces can be transferred by using labour force as well as equipment, and tasks are assembled taking into consideration precedence constraints and cycle time. The decision problem of optimally balancing the assembly work among the workstations is known as the assembly line balancing problem.

Assembly lines can organise production in three different ways: single model, multi-model and mixed-model assembly lines [1, 3]. The design of a single model assembly line is very simple because this type of line is constructed for only one type of product. Different products or different models of the same type of product are assembled on multi-model assembly lines. In this situation, the assembly line balancing problem is solved independently in order to manufacture every lot of the product. In mixedmodel assembly lines, different models of a product are produced at the same time. Mixed-model lines, unlike the single model assembly environment, are designed to assemble more than one model concurrently. Studies of mixed model sequencing have tried to resolve the problem by suggesting sequencing

procedures that optimise various system measures, such as throughput, cycle time, number of stations, idle time, flow time, line length, work-in-process and raw material demand deviation developed heuristics for the balancing–sequencing problem [4].

Assembly line balancing problems can be classified into two groups: stochastic and deterministic assembly lines. When an assembly line is fully automated, all the tasks will have a fixed operation time. Variability (or stochasticity) comes into the picture when tasks are performed manually at the workstations [5].

There can be two main goals while balancing an assembly line [6, 7]:

- 1. Minimisation of the number of workstations for a given cycle time.
- 2. Minimisation of the cycle time for a given number of workstations.

In this study, two heuristic assembly line balancing techniques known as the "Ranked Positional Weight Technique", developed by Helgeson and Birnie, and the "Probabilistic Line Balancing Technique", developed by El-Sayed and Boucher, were applied to solve the problem of multi-model assembly line balancing in a clothing company for two different models. The aim of this article is the comparison of the efficiencies of two different procedures applied for the first time to solve assembly line balancing in a clothing company.

Literature review

The assembly line balancing problem has received considerable attention in the literature, and many studies have been made on this subject since 1954. The assembly line balancing problem was first introduced by Bryton in his graduate thesis. In his study, he accepted the amount of workstations as constant, the workstation times as equal for all stations and work tasks as moving among the workstations [8]. The first article was published in 1955 by Salveson [9]. He developed a 0-1 integer programming model to solve the problem.

COMSOAL (Computer Method of Sequencing Operations for Assembly Lines) was first used by Arcus [10] in 1966 as a solution approach to the assembly line balancing problem.

Helgeson ve Birnie [11] developed the "Ranked Positional Weight Technique". In this method, the "Ranked Positional Weight Value" is determined. It is the sum of a specified operation time and the working times of the other operations that can not be assembled without considering the operation finished. While taking into consideration the cycle time and technological precedence matrix, the operation having the largest ranged weight is assigned to the first workstation, and other operations are assigned to workstations in accordance with their ranked positional weight value.

For the multi-model assembly line, Kilbridge and Wester [12] developed a simple method to solve line balancing. In the first stage they formed an appointment table, and then they made necessary workload balance among workstations, taking into consideration precedence relationships and cycle time.

Nicosio et. al. [13] studied the problem of assigning operations to an ordered sequence of non-identical workstations, which also took precedence relationships and cycle time restrictions into consideration. The aim of the study was to minimise the cost of workstations. They used a dynamic programming algorithm, and introduced several fathoming rules to reduce the number of states in the dynamic program.

Kim et. al. [14] used a genetic algorithm to solve the assembly line balancing problem of how to minimise the number of workstations and cycle time, and how to maximise workload smoothness and work relatedness. A performance comparision was made between the Gas proposed and the heuristic algorithms known.

Experimental procedures

Test materials

In this study, the production of two models: command pocket and welt pocket pants (Figure 1) were investigated to solve the problem of assembly line balancing in a clothing company.

Medhods used

By using the "Ranked Positional Weight Technique" and the "Probabilistic Line Balancing Technique", the assembly line balancing problem was solved. The solution steps of these methods are explained as follows.

Ranked positional weight technique

This heuristic method was developed by Helgeson and Birnie of the General Electric Company in 1961 [11]. In this method, the ranked positional weight value of each operation is determined. The procedures below are applied in order to assign operations to workstations.

The ranked weight value of an operation is obtained by summing the operation time considered with the time of other operations that come after that in series. After all of the ranked positional weights of the operations are determined, they are arranged in decreasing order. Then tasks are assigned to each workstation starting from the task with the highest ranked positional weight. Before this the operation having the second highest ranked value should be selected from the remaining working operations in order to assign to the workstation; the precedence constraints, the operation time, the unused workstation time should be controlled. The assignment procedure is continued until one of conditions below is obtained;

- 1. If all the operations are assigned to the stations,
- 2. If there are no operations having either precedence or unassigned time constraints.

Probabilistic line balancing technique

In this method, a P (predecessor elements) and F (follower elements) matrix are formed and the steps below are followed [15]:

1. The line of the P matrix having zero values is selected. If there is more than one line having zero values, the operation with the highest operation time is selected (Every line corresponds to one work task). If the

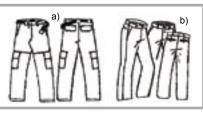


Figure I. Pant model; a) command pocket, b) welt pocket.

time of this work task is suitable, it is assigned to the workstation.

- 2. If the chosen work task is assigned, we go to the F matrix having the same line number and the numbers in this line are taken. Then we turn back to the P matrix and between the subsequent elements of the P matrix in the numbers taken, we write 0 value to the last work task assigned, and step 1 is repeated for the new situation. If the work task is not assigned, we turn back to step 1 in order to open a new station or select a new work task.
- 3. Step 1 and step 2 are repeated until all the lines in the P matrix are used, taking into consideration the constraint (Enb $t_i \le T \le C$).

Results

Model 1: Command pocket pant line balancing results

Model 1: Command pant model ranked positional weight balancing results

This model has fifty-two work operations and an operation list. Its standard times, precedence relations and machine types used are listed in Table 1. After the determination of the precedence relationships between operations, a technological precedence diagram is drawn like Figure 3. Then the cycle time is calculated as shown below:

$$C = T / PA$$
(1)

T = Total working time in a day PA = Total production amount in a day C = T / PA = (540 minutes \times 60 seconds) / 450 piece = 72 seconds/piece

Cycle time = 75 seconds (This value is assumed instead of 72 seconds/piece)

The next step is the calculation of the minimum theoretical number of workstations.

 $n_{min} = Max (n_{min}; n_{probable})$ (2)

$$n_{min} = [\Sigma t_i / C]^+ = [2744.6 / 75]^+ = 37$$
(3)

Table 1. Data of command pant model

SO OFFICATION	NUCHER FOR	RECIDENT RELATIONS	STADARD THE	
PRIPARATIONAL OPPRATIONS				
10 and stilling and tepetiting	Look-retri erwig saciast	+10	21.2	
2)Featpart minlarg	3 decad contacts	+	38,5	
Wrotpatter nede san	Diskle needle zeizegraachter	2	303	
4Digit Brooking	Look-sitch orwing machine		17	
Satema	Lick-stath sewag nachae	+	11.0	
6 Paragering to the Best packet	Exclusion arrang marteer	+ 1	11,8	
TiCoiray Mrs. reegts the free pocket	Cold-stath orwing machine	4	45,1	
82 odat internal	Look-ext orway autam	+	. 21.4	
99Ke packet rearing	Mad auto		21,8	
WPolist fay ten mede out	Disks seeds analyzia late	10	11.2	
USener dale nator	Lock-outh reway anchor with hull-	11	21.1	
TORAce portion preparing and portion edge math	Lots and using softer	10 A 11	M.O.	
R. O. R. PREPARATEON			and the second	
13 Will weeks	2 factal condicit.		1.5	
14 Without	Vitig actor	12	413	
15 Wit opening	Red nak	14	413	
10Wd Ro tout hig	Look sich owing mattine	B	71.4	
17 Webons to the log	Lole-stati energi sacher	36	71.9	
Ulfack probe baging and lary more	Lock-stick orang market	12	311.7	
Tight and product hartering	Datest Matter	18	34.3	
		10	81	
20 Annahing pion down hask potent Men NT MURALATION	Crok-tith invig sachar		-81-	
	Total and many suches	37	94.7	
110 sombling and up officing of Post product facing	Each-stath strateg mathem	31	11.2	
22Change man lanto de Bost podes			31.4	
Digrat poder sign double mails	Traismente mit errageacher	22	21.0	
Wentpolation Mill	Dubla wells mengina hav		714	
25 vot probe hearter	Lob dith owig nation	-		
Milvet point barts mth	Lok-toh ereng sachar	22	31.0	
17Pest polet anothing	Exil-dbit using nation	28	MA	
20 Fost work owhich and but poder lain correction	3 desad-oredick	17	28,0	
29Left to accessite and topoliting	Loketth reing satisf	5,28	51.9	
COGURED+1				
Nilles mittig	D ferral overlick	20.29	41.7	
115kin class rithing	Chair mith mysig suchan	20	412	
120'eret menshing drom hare poskut	Look-tech reway suctaur	31	91,8	
TIE are pocket according	Doda wolk strengtuates	12,12	71,5	
MPIq acesting and spring	Cock-sixts owing nation	11_50	134,0	
25 Flag double meth	Dokir serde inwagsaalaar	24	\$1,6	
Marger availing	Lole-Alth orang maller	15	6.1	
TTP's by Ath	Dokkronde programme		51,4	
Rider & secular	Look-reta reving nuclear	4,32	20.3	
29 Junde by auditack comer mech	d damad combick	38	14,2	
40 Park cente dollo mili	Disking and suggestion	19	30	
41(betting acentiling	Lock sitch owing marhine	40	71,7	
C Value introduce annability	Lolo outh srwag aathar	41	25.9	
Alightuding marilyant	Lock-stath prong names	-42	16.8	
44.Watherd solitable	Lob-stati averg nation	43	31.4	
45 Westwarf back stater label armshing	Lok-reth riving suchar	44	41.1	
44 Categood energy multipal red	Madauk	45	34.6	
47Oogvathal	Lok dth owng nature	45	111.2	
42 and aventing door for belling and ball yorks.	Lick-sith every satisf	0	81.6	
diluting arming over at the orp an ten prote-	Lole-starb orway nation	- 41	2214	
The second second	Dolla confir many carbon		11.7	
11Particing	Datest Matern	50	813	

Table 2. Balancing Results of Ranked Positional Weight Technique for Model 1.

WORKSTATION NUMBER	WORK TASK NUMBER	EXNED POSITIONAL WEIGHT VALUE	PRECEDENCE	OPERATION	CUMULATIVE WORK TIME (0)	EEMAININ TIME (C-E)
	S.C. (1997)	PREPAR	ATTON BACKOP	TRATIONS	1.5701	
1	1.	1998,5		35,3	55,3	19,7
33	13	1913,4		4.6	419	10.1
3	- 14	1917,0	1,00	46,3	403	36,7
	2	1525,5	4	12.0	#6.3	14.7
	4	171,4	1. 14	2,2	44.0	1,0
2,4	10	1878,7	.14	403	44.3	10.7
- 13 - L	14	1834,4	15	73,4	107,7	30,3
		1941,3		31,8	31.8	41,2
	1	1819,7	4	45,1	71.9	3,3
6	1	1834,3	4	36,5	36.5	84,5
-		\$799,7	:	303	51.8	21,2
7	17	1711,0	16	76,9	76.9	4,1
1.1	18	1695,0	17	10.7	101,7	10
and server	19	1578,4	18	343	104.1	13,9
10,11	20	1754,3	29	96,1	90.1	51.9
		\$434,4	· · · ·	32,4	141.7	43
12		1368,5	1	10,8	51.0	21.2
43	10	1017,4		10,2	73.2	21,8
34 82	13	1263.5	10	35.3	79.3	98.7
	10	1942,1		34,0	141.5	4,7
		11	ONT PREPARAT	TION .		
16	21	1798.4	1.6.7	36.7	267	203
	23	1791.0	21	15.8	76.5	43
17	23	1695.0	12	27.4	27.6	47.6
	24	1671,6	23	13.0	764	24.6
10	25	1648.7	24	15.6	12.6	33.4
	24	1011.1	25	11.6	47.2	1.8
15	27	1211.2	26	34.6	34.6	41.4
	28	1544.5	77	25.0	43.6	11.4
34	29	1917,9	5.28	33.9	51.9	20.1
			ASSESSMENT INC			
21	39	1044.0	20 29	43.7	-0.7	213
22,23	30	1420.0	30	46.3	46.3	1817
	10	UTLS.	н	95.8	142.1	1.9
24	30	1278,3	10.12	11.5	71.5	1.2
17 16 17	34	1214,4	10.11	124.0	134.8	181.0
	325	1000.4	34	\$7.6	221.6	3.4
31,29	34	363.8	22	66.8	68.8	81.2
	31	934.0	34	58,4	109.2	31.8
	28	80.7	4,17	15,1	146.4	1,6
34	39	114.6	28	44.2	64.2	11.8
31	43	770.4	29	26,9	26.9	48.1
	- 40	76.5	-40	18,7	46.5	8.6
12,11	42	70.8	41	15.9	21.9	124.1
	43	\$77.9	41	35.8	43.7	60
5.5.10	44	638.2	41	11,4	117.1	12.9
ж	43	796.7	44	48,3	48.3	26.7
12.36	45	538.4	-45	3466	34.6	117.4
	47	503.7	44	111.1	146.8	1.1
17.34.39	44	191.5	41	41.6	81.6	141.4
1.000	- 10	109.5	4	115.4	195.4	28.0
44	- 14	194.4	40	74.1	73.9	1.3
41_42		121.2	50	-104 #L3	83	63.7
		41.0	1	41.0	121.3	24.7

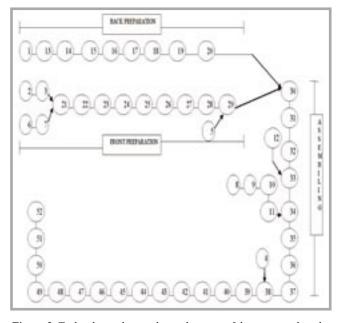


Figure 2. Technological precedence diagram of the command pocket model.

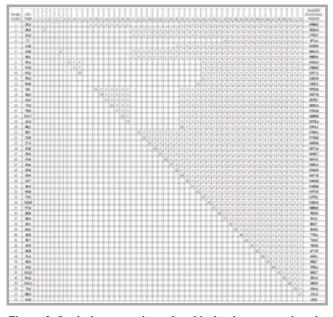


Figure 3. Ranked positional weight table for the command pocket pant model

Table 3. Standard time,	standart	deviation	and	matrix	values
concerning command pan	t model.				

So CHEADON	MACHINE THE	100	VELUE AD VARIADOR	PRATECT	FIGINE
12 ans rithing with preving	Lob-init reng salar	81.3	9.	404	139.0
12P-rel part retries	2 direct controls	1.96/7	+.4	414	20.0
(Diversed we such was	hold with every surface	343	1.9	214	3199
+Bardunya	Lock-text streng texter	1.22		814	3800
SQuit to young	Lob-mit magnatur	11.0	45	0.04	2990
O'rang rough to har paint	2-cit-moti-managementant	34.8	10	408	348
TCostraty Meet using to the free protect	2.48-mm antegrades	403	1.4	4018	2110
12 statuted	Lot and rought	20.4	8.8	101	94.6
19 a post services	East multi	71.9	4.5	404	1100
10 ole lie van wie oan	Doth wells were surface	. 92	1.	. 014	3120
11 Date-in date statur	Lot-met wang nachts with inthis	. 913	4.8	104.0	8450
Collisies product perspansing and product stigs starts.	Lob-mit strong nuclear	54.0	1.4	814	1100
130Mdrowshok	2 dated controls	44	8.4	108	3400
14 Walked	Writing tracings	43	10	124.8	7190
150Mit upming	Destroin P	44.7	11	10-11	2600
10 Web tog togettelling	Lot dol enquater	1.75.4	1.0	124.9	1190
17 Webber and growthing	Lob-mit entry torter	- 910	1.1	194.0	1012
10 Park producting and land man	Lot-mit werg tarbar	111."	1.0	1744	1100
(Plast point bracks	Detect Martine	143	D	1644	2465
20 Generaling piece allow hard pulses	Lob-mit rangeather	46.2	T.P	194.9	1905
21 Normality and topositing of it or poster long	2-d-tell many taskie	56.7	1.1	\$TH	1040
20 Drazegi stati ka to da Brat yo dati	Baltak	171	1.5	2.4.8	2214.8
22 migrate and all and	Ten and still over paint	2.4	D	241	2112
2 Print proder top cards	Colleged and any failer	214	1.4	224.0	2002
20 mg sale happed	Lob-mill every perior	1 11.4	1.4	2410	269.9
A Proposition of the sector	were and many name	Ma	14	840	1144
2 Borry old annulag	Lok-titl string inches	144	14	344	3115
22 at each weight all but publicing commu-	2 detail controls	29-6	84	2718	299.0
20.4 th avenually and improved large	Lob mil song salas	11.9	14	1011	3000
XD# skiles	2 deal red-k	4.	12	28.29.6	8150
12 Date date difficult	Can wet overgrader	#3	1.0	394.9	1249
		190	14	1.11	11110
Silver conding dow has justed	Lob-mix eveng turbar	1.55		2.0+	M112
	and the set of the last	1140	11	122	1044
NPm similar at spin. Title built and	Self-dict religitation	1040	14	10.00	364.9
	Toda and any parties	41	1.0	1041	2120
2 Spow aread by	and the owner parties	314	10	843	8122
IT Pung data	Indianal antiporter			417.1	8990
NCher & annulag	Loi dui respadar	21	12		
25 Sector by an Price in our relation	7-divel controls	942		1944	4990
Cash one freis and	2-Alt or D orng tailan	- 82	LU I	211	4122
el bet tra entetta.	Lot-text every netwo	54.7	1.0	4010	4211
C/Dateparty/si antiling	Lok-stri stargischer	25.9	- 13	6.4.8	43.0.0
Cittalag variat	Lob dei antersche	718	7.4	411	0000
#Wat-mininkig	Lob mit sweg seler	36.4	4.5	4011	4530
C. Wartani Turk inter Mittaren Ba	Lot dil engador	- 42	62	0.11	4022
to induce a second s	Sectors'	144	14	611	47.00
(Congrantial	Lob-tolk rowag taskar	142.2	12	647	4222
di Lake unesting dros its het ing addrest proter	of the set		16.5	4.4.0	49(1)
40 https://www.integ	Lob-mix responder	1054	W.	.4013	346.0
X/Leg beartists	Doklarski svognacian	174	- 10	841	3100
12 Faterlag	Distant Manham	803	1°	364.8	3200
Siller and a second sec	But with Marlens	41.8	2.54	2.49	014

Table 4. Probabilistic line balancing results of the command pocket	ţ
pant model.	

Station munber (k)	Mark task to Number		7.	Unnsed
	1	55,3		C)
1	13	6,6	61.9	12,1
2	1.4	1416,28		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
		7.7		
	2	12,0	6.0	7
3	15	44.3	44,3	30,7
-4	16	73.4	73,4	1,6
	12	70,9	70,9	-4,1
	18	111.7	Sec. and	
6.7	19	24.3	136.1	13.9
	50	90,1		1.
8.9	8	55,4	149,5	4.5
10	2	51.0	21.0	23,2
11	10	53,2	53,2	
12	11	59,3	59,3	15,7
12	2 3	20,5		
12		24,3	54.0	20.2
1-4	6	31,8	31,8	43,3
	12	40,1		
15.16	21	84,0	124.1	25.9
	22	50,7	100.0	
12	22		70.5	4.5
	214	22.0		
18	22	35.6	50,4	24,6
19	26	31,6	67,2	7,6
	27	34.6	45.7.116	P 1 10
20.	20	29.0	63.6	11.4
21	3.9	53,9	53,9	21.1
22	30	42.7	43.7	31.3
	21	46,3		
22_24	32	90,8	142.1	7,9
9.5	33	73.5	73.5	1.5
26_27	34	124.0	1 214	26
28.29	34	97,6	97,6	52,4
30	3.6	68.8	68.8	6.2
31_32	37	50.4		
	30	89.1		
	39	64.2	143,7	6,3
33_34	40	26,9		
	41	39,7		
	-412	25.9	92.5	57.5
35_36	-43	59,0		and the second se
	44	31.4		
	45	40.3	139.5	10.5
	46	34.6		
37.38	47	112.2	146.8	3.2
	-4.0	83.6		1
39 40 41	-49	115.4	197.0	28.0
-4.2	50	72.2	73,2	1,0
	51	80,3	10000	1
10.00 -0.00	52	41.0	121.3	28.7

Table 5. Operations, ranked positional weights and machine type used for the welt pocket pant model.

WORK TAFE SUBGER	STD TD4	RANCED POSITIONAL VEICHT	OPEATIONS	MAX HERE TAPE
	1.		PERPARATIONAL OPERATIONS	
2	23,6	1401.1	Break prodet Secan assau	Lock-risch overage machine
1	417	144.1	Producer man	Lock-rest orweg nation
	22.7	1408,8	Standy whet minute	Lick-mill sewig satisf
2	-40,4	1406,4	Front perfort bale for evolving	Lock-relationing marhine
4	38,7	1985,9	With surfack	O-farted overlock
5	3,8	1228,1	Prod with risks?	3 Retoil overlinik
3	2,9	104.8	Right to annual	Titletad universiteda
7	3,6	1,519	Kall Scone	Lod-mit averg nuclear
	2.6	342,6	Let by yong	Lock-text orweg surface
			PROOF PREPARATEON	
- 84	42.9	1035,3	Frost manet probet accessible and try electing	
10	37.8	1391.8	Manutp-skethaging	Lock-real, erwag sachar
84	11.8	1955,2	Assessment of Boost processed Suring	List-this wang surface
10	42.0	1301,8	Front pocket facing topaththang	Lode-medi-sewig warbar
. 11	52,0	1261.9	Fichet logging	Lock-mit overgeacher with lad
19	483	1209,9	The restanced the approximiting	Lock-thelorweg nation
10	73,7	1313,6	From product according	Lod-oblaring nation
21	18,1	1095,9	Let be accepting	Loth-rich-sering nachae
			BACK PERPARADON	
10	11.4	1224,8	Back parket weiling	Writing machine
83	10.7	1960,3	Finance top-stating of web	Lob-not sewig softer
10	10.0	1110.0	Top mitting of yold	Lock-mick orang machine
10	61,2	URDE	Back product bagging and top sticking	Lock-owi orweg nation
	0.21.2	1.000	A9985484290	
22	63,0	107.1	Tage working	Lock other orways marking
22	54.0	997,3	The retained for	Lick-rect erwag sachar
- 24	18,9	543,8	Right by second long	Lot out orang autain
18.	24.5	382,3	Side inset	S-fartad overlock
24	943	138.4	Sele chan an deg	Chan stab revenue to a free
27	509	04.2	field loop asserting	Lock-risk overg nation
28	101.1	249,3	Kathad availag	Lok-mo.ormgasias
- 25	-44,6	69,3	Washeding and set	Lock-risch sewing machine
31	72.0	194.5	Wathout out annohing	Lock-ritel, erwag aactaar
81	80.3	125.6	Wart-aul long timber	Lob out average autor
14	29,8	4415	Front options and windows instruction fitting	Lob-rock arrive surface
10	-422	-410	Back coster binding ware (best ream)	Chaits ritch coming trachine
34	46,7	389,6	fronte by burden men	S famil centrals
19	17,9	342.3	Back, restor accessibly ream	Lok-mix rengentiar
36	61,7	325.0	Washaad end making and clounse	Lod-mitorweg sucher
17	12.1	263,4	Washaul must closure faitning	Lod-rick erving author
10	49.3	11(3	Troop Institute	Lob-rish oreirg nother
- 28	41,2	2263	Probellanking	Januti Malari
-46	63,7	45.7	Belt loop hortacking	Bartick Michael

Table 6. Model 2: Ranked positional weight balancing results of the welt pocket pant model.

WORRATATION NUMBER	WORK TANK NUMBER	RANEED POSITIONAL WEIGHT VALUE	PRECEDENCE	OPERATION THE	CUMELARNE WORK TIME (20	RENLINEN TIME (C-3)
		1812-	RATIONAL OPP	RATIONS		
1	3	1412.2		23.6	21.6	41.4
		1016.0		1.9	24.5	16.5
1	1	1918.1		41.7	41.7	23.3
	6	1416.6	3	22.7	21.7	423
	1	1228.7		1.8	24.8	16.5
	1	971.8		9.6	H.I	18.9
4	1	1426.4	1	45.4	10.4	34,6
1		1345.5	1	10.7	36.7	34.3
		945.4		3.6	34.8	30.7
			CONT PREPARA	THORN		
6	14	1033	3.6	41.9	41.8	11.8
1	17	LIPER	14	17,8	27.8	314
	16	1895.2	124.0	. 51,3	21.3	0.7
	17	1100.5	14	42.0	41.8	11.0
18	18	1261.9	17	32.0	31.8	11,0
11	19	1219.5	18	40.3	46.3	24.7
12,13	38	1045.6	39	71.7	11.7	14,3
	11	1045.5	9.20	16.1	111.8	18.2
			ACK PREPARAT	TION		
14	18	1114.8	1	M.4	11.4	5.6
15	- 11	1049.3	18	38.3	36.5	34.7
	12	1029.0	11	18,0	46.3	16,7
14	13	1121.0	12	40.2	61.2	1.8
			ASSEMBLE	G .		
17	13	1017,0	88,20	44.3	66.3	2.4
18	23	1911.0	22	54.0	54.8	11,0
	24	943.8	8.23	18,9	64,9	1.0
19	25	101.9	34	50	10	31.5
	26	876,8	33	543	126.8	1.1
- 29	. 19	894,2	36	34.9	54,3	1.0
21,22	25	163	27	199.1	890.8	29.9
23,24	29	649,2	28	44,6	44,8	87,4
	38	404.6	29	79.0	128.6	6.1
11	34.	733,4	30.	44,8	64,3	6.8
36	10	-011,5	11	25,8	28,8	35,2
27	.19	-01.0	- 32	42.2	41.2	11.8
38	34	389,6	19	46,7	46,7	14,3
10	.15	342.9	34	17.9	64,5	6.4
19	36	325,8	18	40,7	61,7	1,3
26,21	37	263,8	36	87,1	17.1	42,9
11	18	1%2	17	45,3	44.3	18,7
33,34	38	1363	38	41.3	61.2	66.8
1. San 1.	40	61.7	29	48.7	826.5	3.1

Neatins	Work task (0 Funder			time ed
1	1	41.7	41.7	
	2	10.4	40.4	2-6,40
		22,6		10 mm 10
	-1	30,7	24.2	10.7
	. 5	34,68	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	2010/00/202
	6	83.7		
	7	9.6		
	0	3,6		
		2,9	42,6	22.4
5.	30	55,4	39,4	52,45
6	11	30,4		1. 2 March 1. 1
	3.9	3.0.0	49.4	16,6
	.12	63.8	63,2	3,0
	1-4	-422.54	431.9	32.1
	1.2	37.8	27.8	37.2
10	3.6		- 51,2	13.7
1.1	1.5		48.0	-23,0
1.22	10	- 52.0	52.0	13.0
12	19	-40,3	40,3	24.7
14-15	20	23.7	· · · · · · · · · · · · · · · · · · ·	
	21	20.1	111.0	10.2
10	. 55	0,08	60.0	5,0
17	23	54,0	54,0	11,0
18-19	- 954	10,9	1.1.2.2.2.1.1.1	
	85	34.5	05,4	44.6
20	26	54,3	54.3	10,7
21	27	5-8,54	5-8,9	10,1
22-23	28	100.1	100.1	29,9
04-05	59	1818,16	1002-0-5-5	
	30	79,0	123.0	6,4
56-57	21	64.1		
28	- 28	29,8	93.9	36.1
	3.3		49,9	32,8
819	- 34	46,7	46.7	10,9
30-31-32	35	17,9		
	36	61,7		
	37	87.1	146.7	15,7
22	28	40.3	49.2	12,7
34-33	39	61,2	126.9	2.3

Table 7. Model 2: Welt pocket pant probabilistic line balancing results.

Table 8. Line balancing results.

Model	The number of workstation	Theoritical line efficiency, %	Line efficiency, %	Balancing loss, %
Command and pocket pant- ranked positional weight method balancing results	n = 42	98.9	87.1	12.9
Command and pocket pant- probabilistic method line balancing results	n = 44	98.9	83.2	16.8
Welt pocket pant- ranked positional weight method balancing results	n = 34	97.9	80.6	19.4
Welt pocket panl- probabilistic method line balancing resuits	n = 35	97.9	78.3	21.7

 $n_{probable}$ = The number of work tasks that have the condition of $t_i > (C/2 = 75/2 =$ = 37.5) = 33 (1,7,8,9,10,11,12,14,15,16, 17,18,20,21,29,30,31,32,33,34,35,36,37, 39,41,43,45,47, 48,49,50,51,52)

 $n_{\min} = Max(37; 33) = 37$

Then ranked positional weights of operations are calculated by using the method explained above and listed in a descending order, as shown in Figure 4. As a result of balancing, it is found that (n = 42) workstations are needed to balance the line. This situation is convenient for the condition ($n \ge n_{min}$). Balancing results of the ranked positional weight technique are given in Table 2.

Balancing loss is calculated:

$$BL = (n \times C - \Sigma t_i)/(n \times C) \times 100\% =$$

= (42×75 - 2744.6)/(42×75)×100% =
= 12.9% (4)

For this assembly line, theoritical and real line efficiency values are calculated:

$$TE = \left[\sum_{i=1}^{N} t_i / (n_{\min} \times C)\right] \times 100\% =$$

$$= \left[2744.6 / (37 \times 75)\right] \times 100\% = 98.9\%$$

$$LE = \left[\sum_{i=1}^{N} t_i / (n \times C)\right] \times 100\% =$$

$$= \left[2744.6 / (42 \times 75)\right] \times 100\% = 87.1\%$$
(6)

Model 1: Command pocket pant probabilistic line balancing results

Table 3 shows information about the standard time, standart deviation and precedence matrix of the model. By

accepting the confidence interval as being 80% and the cycle time as being C=75 seconds, we can attempt to balance to balance the assembly line. After constituting P and F matrixes, the steps below are followed:

- 1. We start by using the first line, having only zero values in the P matrix. The first operation is assigned to the first station (t_1 =55.3; T_1 =55.3).
- 2. We take 13 from the first line of the F matrix. It is looked to the line 13 of the P matrix. There is a value of l, this means that before 13 is assigned to any workstation, operation 1 should be made. This situation is supplied above. Operation 13 is controlled in order to assign it to a workstation.
- 3. Z formula is used to control the suitability of operation 13 for the workstation (t_{13} =6.6, T_1 =62, $Z_{20\%}$ = -0.84):

As the confidence interval is 80% (= 50% + 30%), a value corresponding to 30% (= 0.3000) is sought from the normal distribution table that the value corresponding. This value is 0.84. However, here the non-confidence value which corresponds to (1 - 80% =) 20% is sought, and this value is $(Z_{20\%} = -0.84)$.

$$\sigma_{\text{w.s.}} = \sqrt{\sigma_1^2 + \sigma_{13}^2} = \sqrt{(7.1)^2 + (0.4)^2} = 7.11$$
(7)

$$Z = (62 - 75)/7.11 = -1.82 < -0.84 \quad (8)$$

 $P(T > C) \approx 0 < 0.2$ (assignment is available).

4. If there is still unused cycle time, it is sought whether or not any other work task can be assigned to the first station. If an operation can not be assigned to a station, then a new station is opened and new operations are attempted to be to assigned.

Table 4 shows command pocket pant model probabilistic line balancing results of the command pocket pant model. The balancing loss and line efficiency are also calculated below:

$$BL = (n \times C - \Sigma t_i)/(n \times C) \times 100\% =$$

= (44×75 - 2744.6)/(44×75)×100% =
= 16.8%
$$LE = [\sum_{i=1}^{N} t_i/(n \times C)] \times 100\% =$$

= [2744.6/(44×75)]×100% = 83.2%

Model 2: Welt pocket pant line balancing results

Model 2: Welt pant model ranked positional weight balancing results

First the cycle time is calculated. Table 5 shows the operations, ranked positional weights and machine types used to produce the welt pocket pant model.

$$C = T/PA = (540 \text{ minutes} \times 60 \text{ seconds}) / 500 \text{ piece} = 64.8 \text{ seconds/piece} = 65 \text{ seconds} n + = Max (n + i n + i n + i n) = 28$$

$$n_{min} = Max (n_{min}; n_{probable}) = 28$$

The line is balanced by using (n = 34) workstations. Balancing results of the

ranked positional weight technique are given in Table 6.

$$TE = [\sum_{i=1}^{N} t_i / (n_{min} \times C)] \times 100\% =$$

$$= [1781.8/(28 \times 65)] \times 100\% = 97.9\%$$

$$LE = \left[\sum_{i=1}^{N} t_i / (n \times C)\right] \times 100\% =$$

Model 2: Welt pocket pant probabilistic line balancing results

Welt pocket pant probabilistic line balancing results are shown in Table 7. Also, line balancing loss and real line efficient values are calculated below:

$$BL = (n \times C - \Sigma t_i)/(n \times C) =$$

= (35×65 - 1781.8)/(35×65) = 21.7%

$$LE = [\sum_{i=1}^{5} t_i / (n \times C)] \times 100\% =$$
$$= [1781.8 / (35 \times 65)] \times 100\% = 78.3\%$$

Conclusions

As a result of evaluation, it can be seen that the Ranked Positional Weight Technique gives better resuls than the Probabilistic line balancing technique, as shown in Table 8.

The Ranked Positional Weight Technique is easier to apply and has higher line efficiencies. On the other hand, it is accepted that task times are not deterministic (variable) and work element times obey a normal distiribution with µ average value and σ standard deviation in the probabilistic line balancing technique. For this reason, when work elements are assigned to workstations, standard deviation values of standard time values are taken into consideration. This situation enables work elements to be assigned to workstations more sensitively, and thus more reliable assembly line balancing results can be obtained. In conclusion, both techniques have proven effective in getting successive line balancing results and it is necessary to select between them in accordance with the company's targets.

Editorial note

This problem was also presented at the 2006 AUTEX Conference, June 11-14 2006, Raleigh NC State University.

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